

## Vorlesungsplan GuG SoSe 2023 - Vertiefung Navigation und Umweltrobotik

|    |      | Sem. | 8  |    |    | 9   |    |   | 10  |    |    | 11  |    |    | 12  |    |    | 13                                   |    |    | 14 |    |    | 15                                   |    |    | 16 |    |    | 17                               |    |    | 18 |    |    |
|----|------|------|--|----|----|---|----|---|---|----|----|---|----|----|---|----|----|--------------------------------------|----|----|----|----|----|--------------------------------------|----|----|----|----|----|----------------------------------|----|----|----|----|----|
|    |      |      | 15   | 30 | 45 | 15  | 30 | 45  | 15  | 30 | 45 | 15  | 30 | 45 | 15  | 30 | 45 | 15                                   | 30 | 45 | 15 | 30 | 45 | 15                                   | 30 | 45 | 15 | 30 | 45 | 15                               | 30 | 45 | 15 | 30 | 45 |
| Mo | NuUR | 1    |  |    |    |   |    | Recursive State Estimation Dyn.<br>V2 Alkhatib B046 |   |    |    | Image analysis I<br>V2/Ü1 Rottensteiner / Kanyamahanga V105 |    |    |   |    |    | Robotik II<br>V2 Mohammad 030 (8130) |    |    |    |    |    | Robotik II<br>Ü1 Mohammad 030 (8130) |    |    |    |    |    | Image Anyl.I<br>V2/Ü1 Rott. A255 |    |    |    |    |    |
|    |      | 2    |  |    |    |   |    | Recursive State Estimation Dyn.<br>V2 Alkhatib B046 |   |    |    | Image analysis I<br>V2/Ü1 Rottensteiner / Kanyamahanga V105 |    |    |   |    |    | Robotik II<br>V2 Mohammad 030 (8130) |    |    |    |    |    | Robotik II<br>Ü1 Mohammad 030 (8130) |    |    |    |    |    | Image Anyl.I<br>V2/Ü1 Rott. A255 |    |    |    |    |    |
|    |      | 3    |  |    |    |   |    | Recursive State Estimation Dyn.<br>V2 Alkhatib B046 |   |    |    | Robotik I<br>V2 Matthias Müller 023 (3703)                  |    |    |   |    |    |                                      |    |    |    |    |    |                                      |    |    |    |    |    |                                  |    |    |    |    |    |
| Di | NuUR | 1    | Geosensornetze<br>V2 Sester / Feuerhake GS-Labor     |    |    | Grundlagen GNSS u. Navig.<br>Ü2 Schön / Kröger V404 |    |   | Erweiterte Bereiche der Geodäsie<br>V2 Voß B046 |    |    |   |    |    | Geodätisches Hauptseminar<br>SE siehe Aushang A 104                   |    |    |                                      |    |    |    |    |    |                                      |    |    |    |    |    |                                  |    |    |    |    |    |
|    |      | 2    | Geosensornetze<br>V2 Sester / Feuerhake GS-Labor     |    |    | Grundlagen GNSS u. Navig.<br>Ü2 Schön / Kröger V404 |    |   | Erweiterte Bereiche der Geodäsie<br>V2 Voß B046 |    |    |   |    |    | Geodätisches Hauptseminar<br>SE siehe Aushang A 104                   |    |    |                                      |    |    |    |    |    |                                      |    |    |    |    |    |                                  |    |    |    |    |    |
|    |      | 3    | Geosensornetze<br>V2 Sester / Feuerhake GS-Labor     |    |    |   |    |   |   |    |    |   |    |    |   |    |    |                                      |    |    |    |    |    |                                      |    |    |    |    |    |                                  |    |    |    |    |    |
| Mi | NuUR | 1    |  |    |    | Grundlagen GNSS u. Navig.<br>V2 Schön V404          |    |   | Erw. Bereiche der Geodäsie<br>V2 Müller V404    |    |    |   |    |    |   |    |    | Robotik I<br>Ü1 Lilge 023 (3703)     |    |    |    |    |    |                                      |    |    |    |    |    |                                  |    |    |    |    |    |
|    |      | 2    |  |    |    | Grundlagen GNSS u. Navig.<br>V2 Schön V404          |    |   | Erw. Bereiche der Geodäsie<br>V2 Müller V404    |    |    |   |    |    | Projektseminar<br>SE 4 GIH (A260), IFE (V404), IPI (V105), IKG (611A) |    |    |                                      |    |    |    |    |    |                                      |    |    |    |    |    |                                  |    |    |    |    |    |
|    |      | 3    |  |    |    |   |    |   |   |    |    |   |    |    | Projektseminar<br>SE 4 GIH (A260), IFE (V404), IPI (V105), IKG (611A) |    |    |                                      |    |    |    |    |    |                                      |    |    |    |    |    |                                  |    |    |    |    |    |
| Do | NuUR | 1    | Recursive State Estimation Dyn.<br>Ü2 Mofizadeh A260 |    |    |   |    |   |   |    |    |   |    |    |   |    |    |                                      |    |    |    |    |    |                                      |    |    |    |    |    |                                  |    |    |    |    |    |
|    |      | 2    | Recursive State Estimation Dyn.<br>Ü2 Mofizadeh A260 |    |    |   |    |   |   |    |    |   |    |    |   |    |    |                                      |    |    |    |    |    |                                      |    |    |    |    |    |                                  |    |    |    |    |    |
|    |      | 3    | Recursive State Estimation Dyn.<br>Ü2 Mofizadeh A260 |    |    |   |    |   |   |    |    |   |    |    |   |    |    |                                      |    |    |    |    |    |                                      |    |    |    |    |    |                                  |    |    |    |    |    |
| Fr | NuUR | 1    |  |    |    |   |    |   |   |    |    |   |    |    |   |    |    |                                      |    |    |    |    |    |                                      |    |    |    |    |    |                                  |    |    |    |    |    |
|    |      | 2    |  |    |    |   |    |   |   |    |    |   |    |    |   |    |    |                                      |    |    |    |    |    |                                      |    |    |    |    |    |                                  |    |    |    |    |    |
|    |      | 3    |  |    |    |   |    |   |   |    |    |   |    |    |   |    |    |                                      |    |    |    |    |    |                                      |    |    |    |    |    |                                  |    |    |    |    |    |

Bei externen Veranstaltungen bitte immer auf die Aushänge der jeweiligen Fachrichtung achten!

<http://www.gug.uni-hannover.de>

|                |                    |      |
|----------------|--------------------|------|
| Geosensornetze |                    |      |
| Ü1             | Sester / Feuerhake | n.V. |